

Università degli Studi di Padova – Dipartimento di Ingegneria Industriale

Corso di Laurea in Ingegneria Dell'Energia

***Relazione per la prova finale***  
***«Negative Ion Beam profile estimation on***  
***STRIKE calorimeter by means of Newton's***  
***Method »***

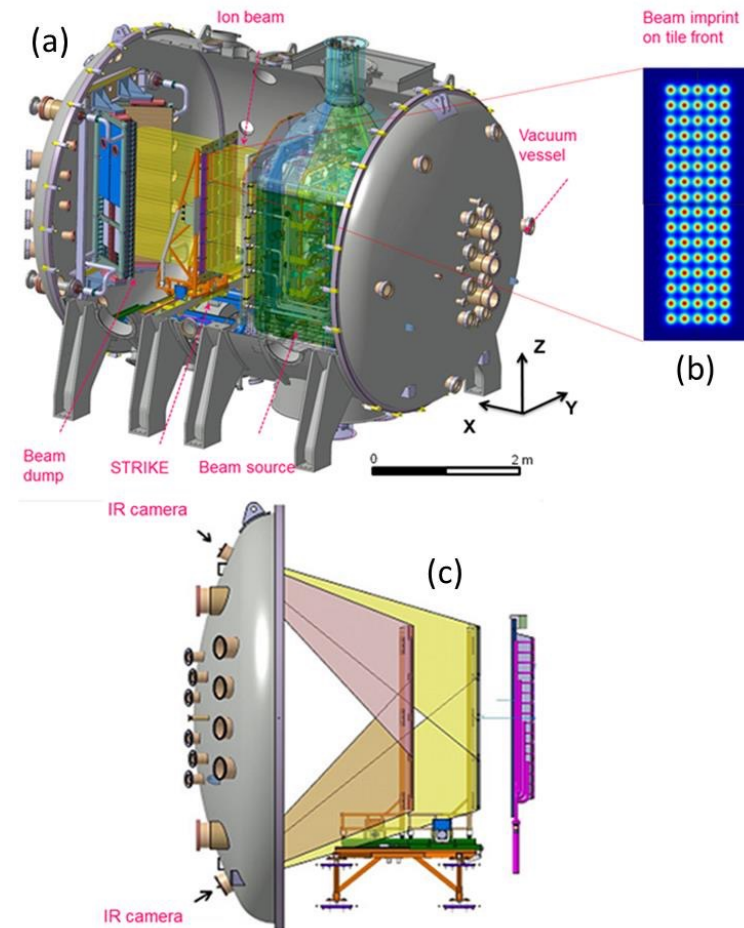
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Padova, 28/09/2023

- What is Spider?  
Spider is a negative ion source prototype to heat plasma on ITER, a fusion reactor located in Cadarache, France.  
It produces negative ions beams of Deuterium and Hydrogen with a current density of respectively:  $258 \text{ A/m}^2$  e  $355 \text{ A/m}^2$



STRIKE stands for Short-Time Retractable Instrumented Kalorimeter; it is the instrument by which the beam of SPIDER will be investigated.

**SPIDER BEAM DUMP FACTS**

**Objective**  
To reconstruct and characterize the energy flux of the Ion Source SPIDER

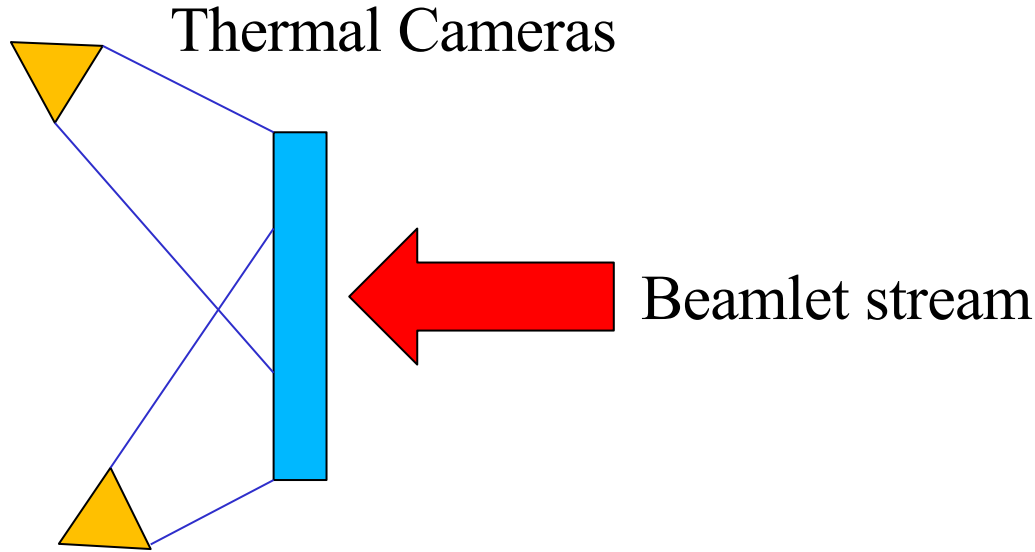
**Components**  
One-directional carbon fiber - carbon composite tiles

**HOW IT WORKS**  
The tiles that composed Strike are hit by the beam, and a thermal camera on the backside record the tiles temperature in order to profile the neutral beam intensity.

STRIKE has spatial resolution of about 2 mm

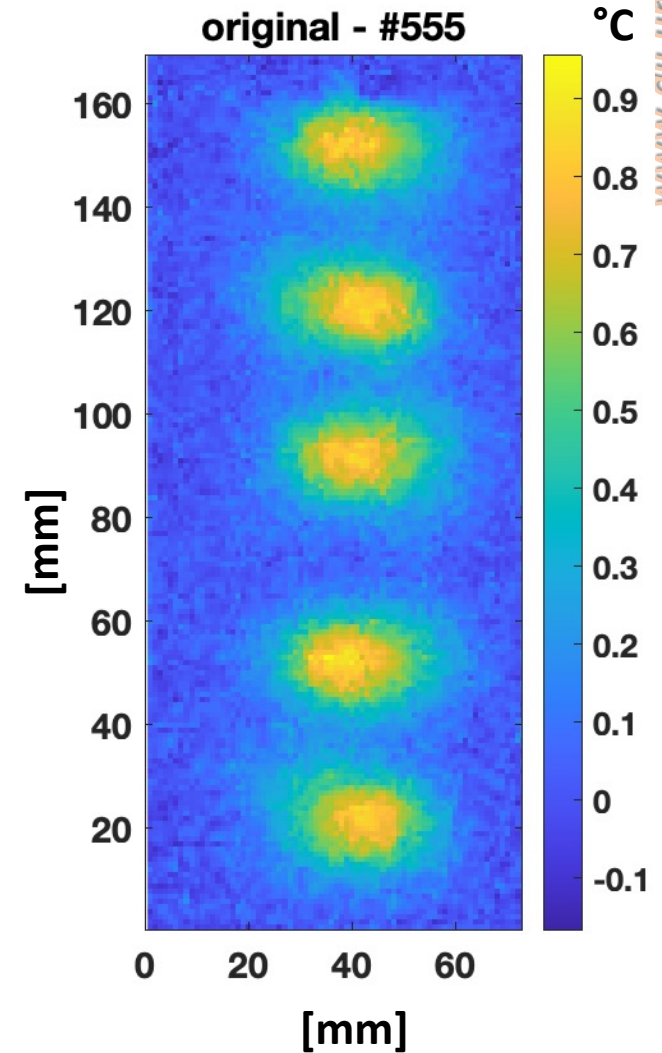
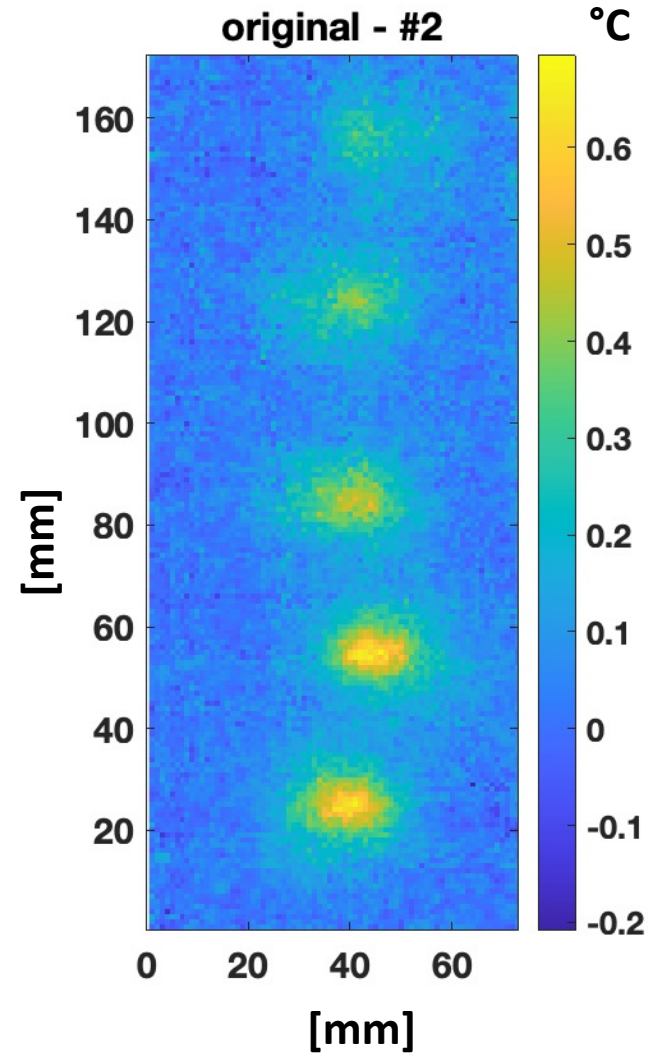
Closed experiment      Open experiment

- What is STRIKE?  
STRIKE is a calorimeter and the main diagnostic system on Spider, designed to characterize the negative ion beam in terms of uniformity and divergence.  
16 one way graphite tiles.



- $$T = \sum_i \sum_s A_s e^{-\frac{1}{2} \left( \left( \frac{x_i - x_s}{\sigma_{x_s}} \right)^2 + \left( \frac{y_i - y_s}{\sigma_{y_s}} \right)^2 \right)}$$

$i = \text{pixel number};$   
 $s = \text{beamlet number}$
- Project objective:** to provide a tool that can be used during experimental sessions to derive the meaning parameters of the beamlets very quickly



- Two database types: Synthetic and Experimental Images – 573 images for both;

- Method Steps:**

$$J = \frac{1}{2N} \sum_N (T - T^*)^2$$

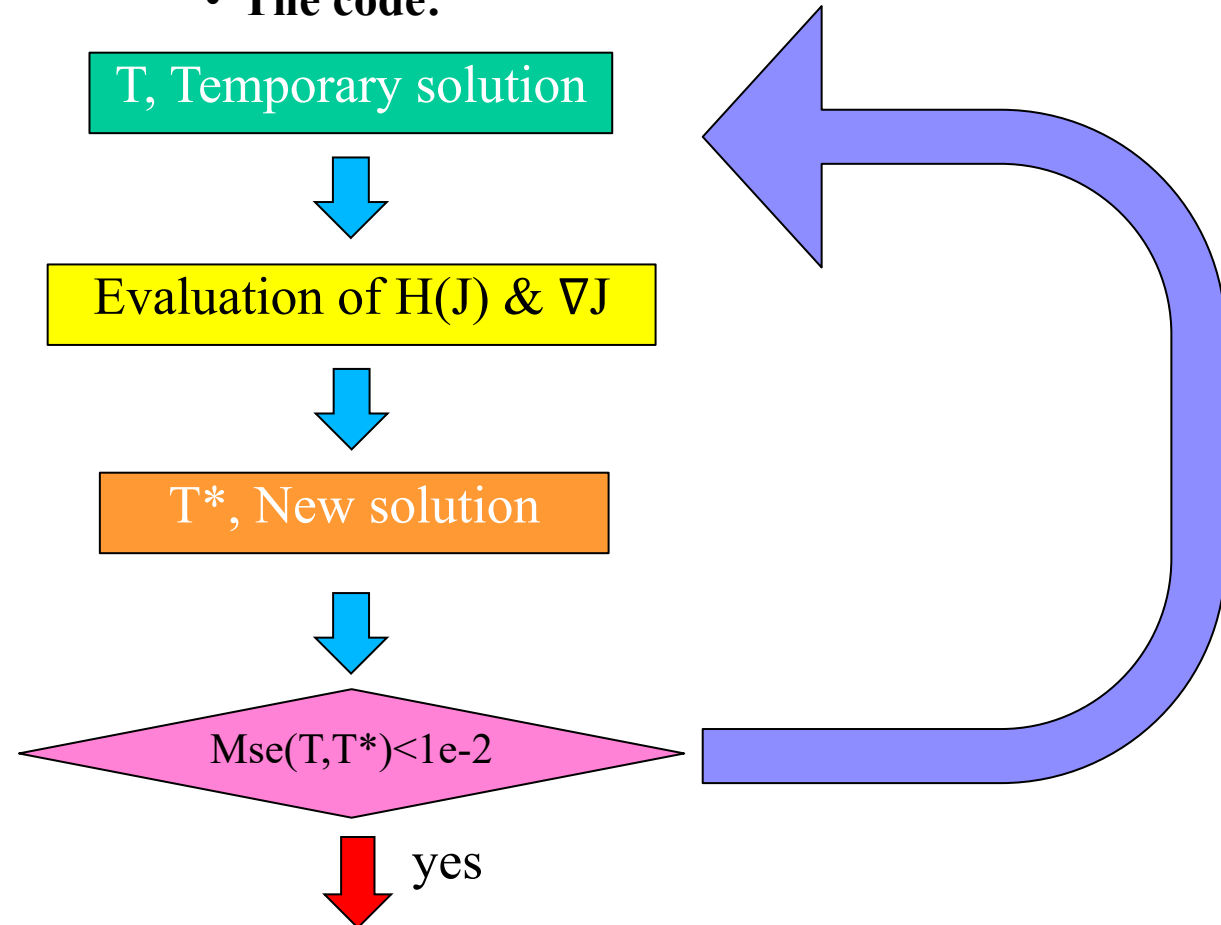
...If  $\begin{cases} J'(A, x, y, \sigma_x, \sigma_y) = 0 \\ J''(A, x, y, \sigma_x, \sigma_y) > 0 \end{cases}$  ;  $H(P^*) \geq 0$

$\Rightarrow P^*$

Otherwise:

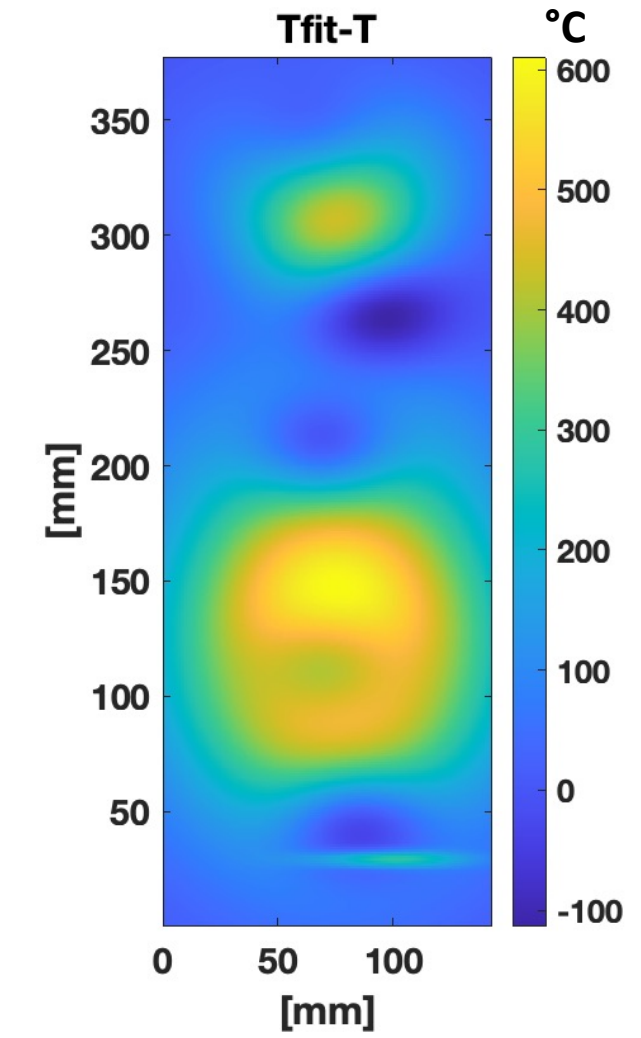
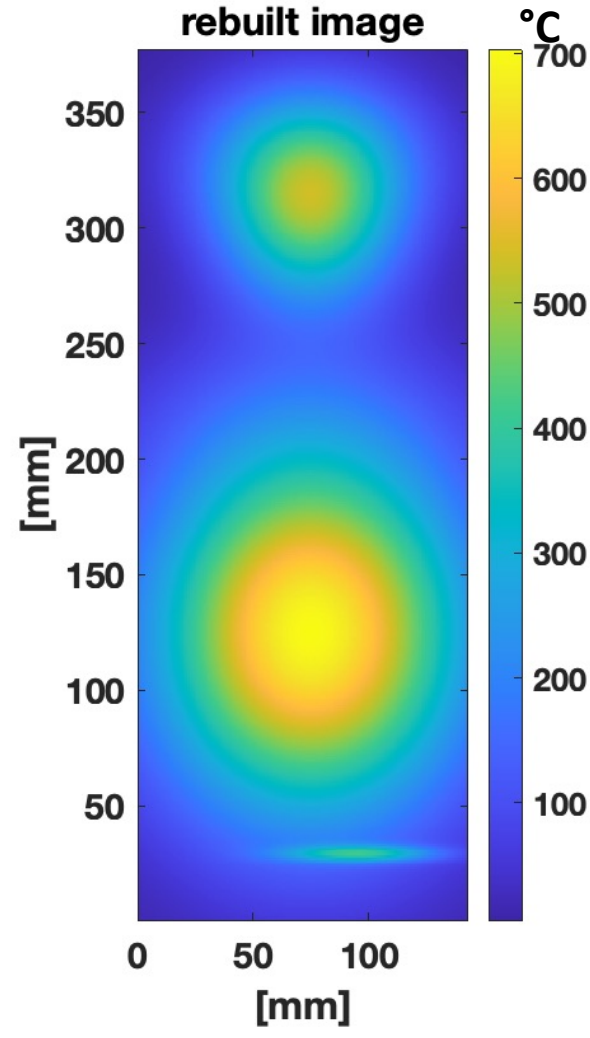
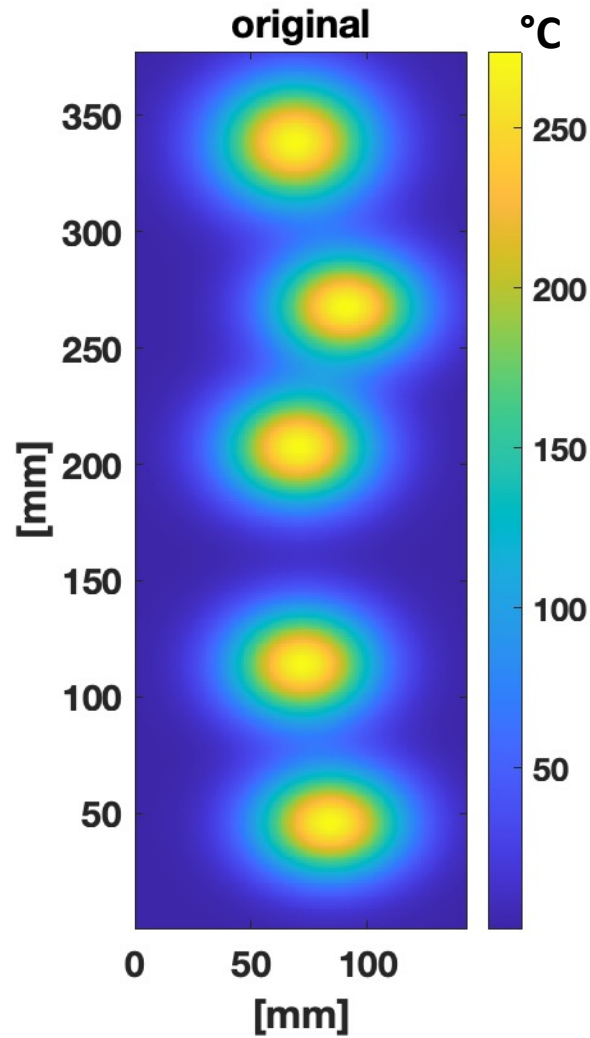
$$T(k + 1) = T(k) + \alpha * \delta(H(J), \nabla(J))$$

- The code:**

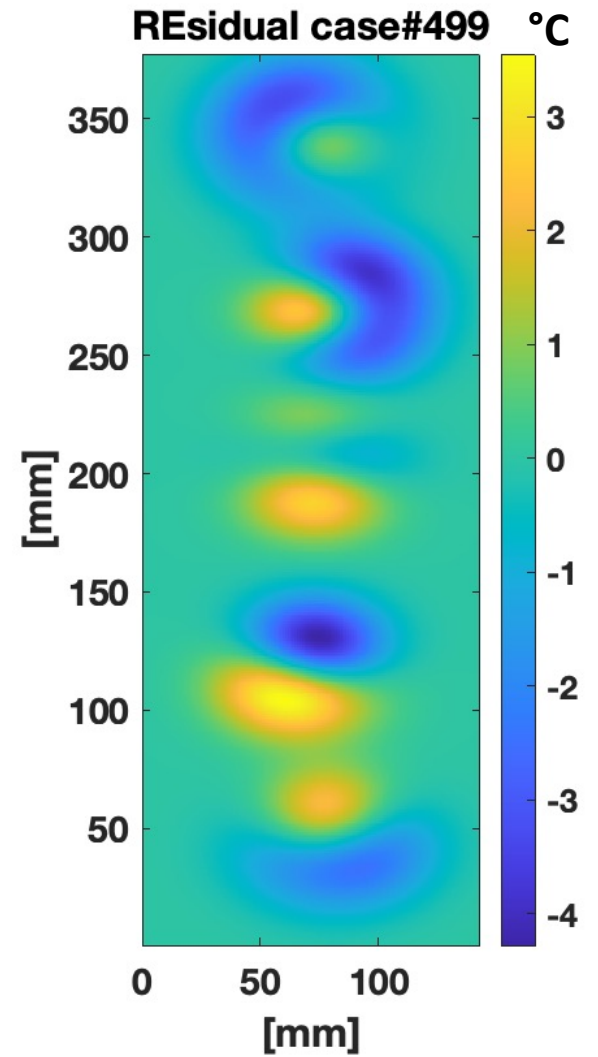
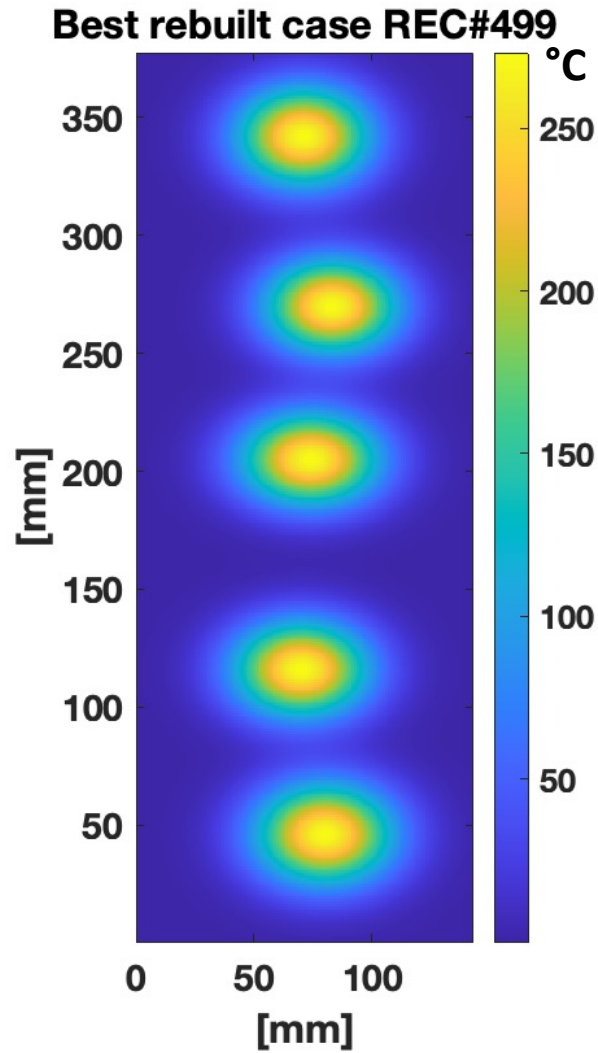
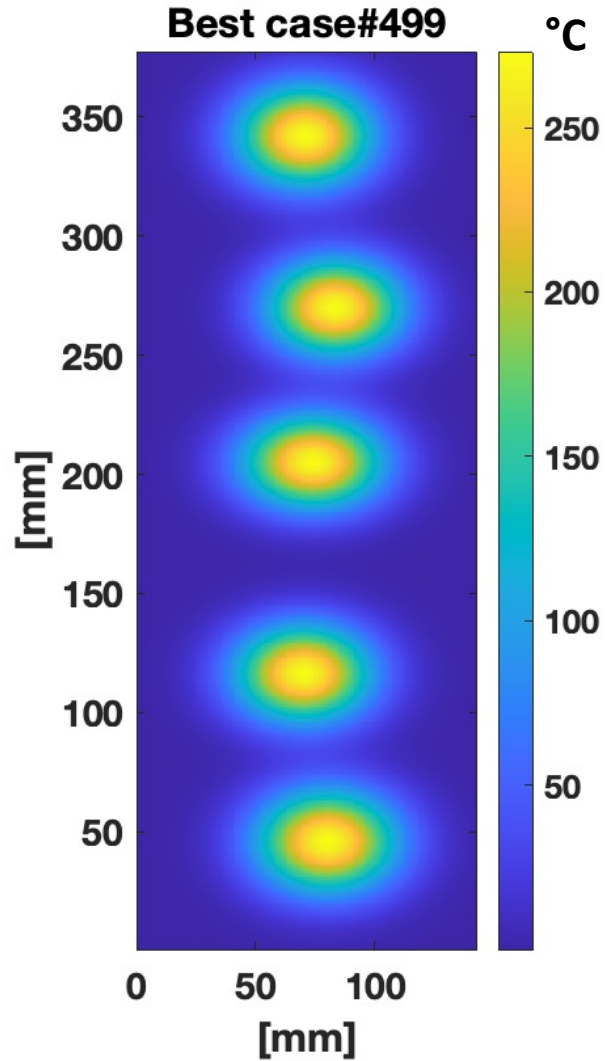


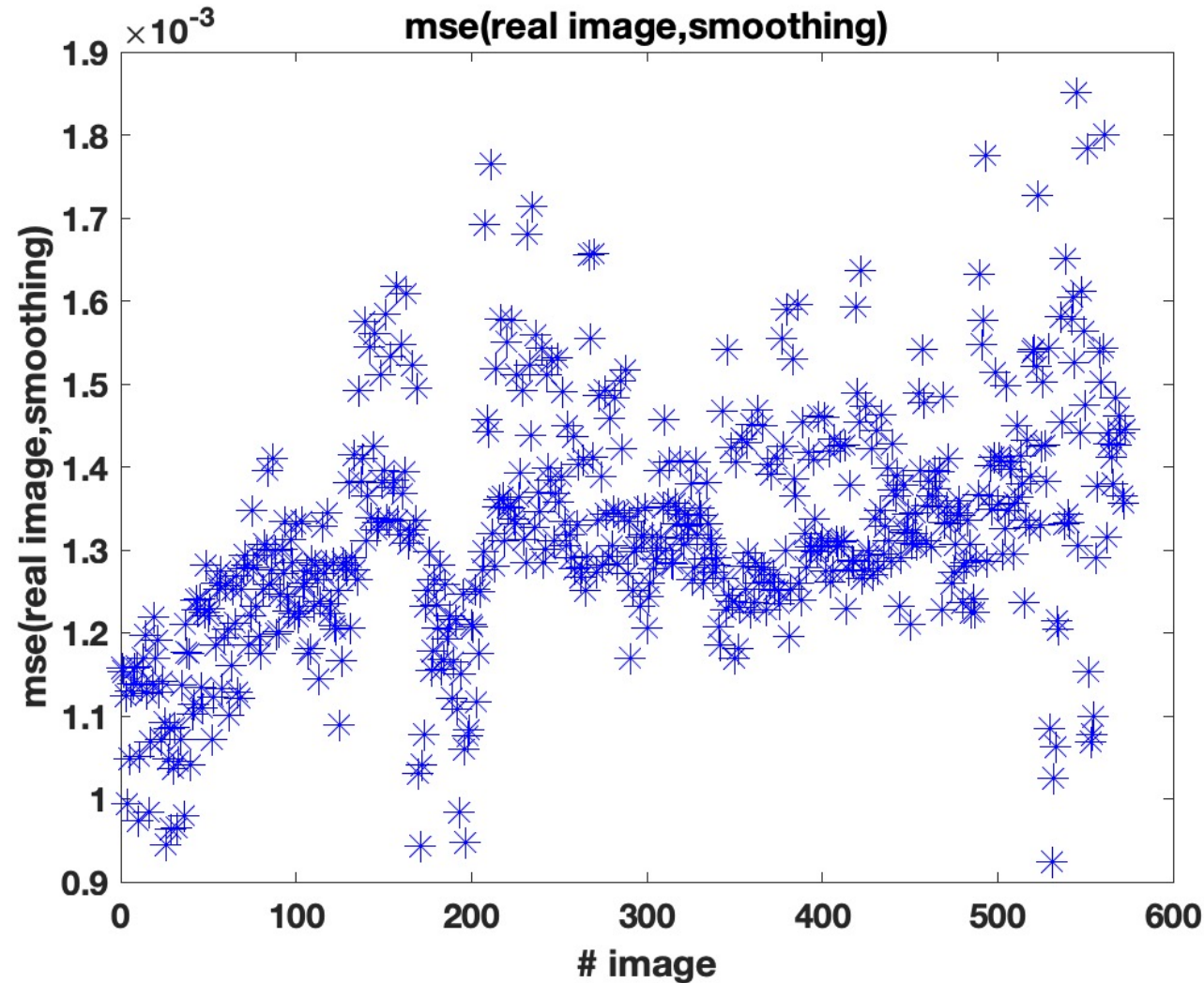
- esc if  $\text{mse}(T, T^*) < 1e-2$ ;
- $\alpha = 0,005$
- except for image n°546
  
- Mean Error Reconstruction:
  - Amplitude = 0.91%
  - $x_0 = 9.5e-04\%$
  - $y_0 = 0.0011\%$
  - $\sigma_x = 0.0103\%$
  - $\sigma_y = 3.82\%$

Worst Image: n°546



Best Image: n°499





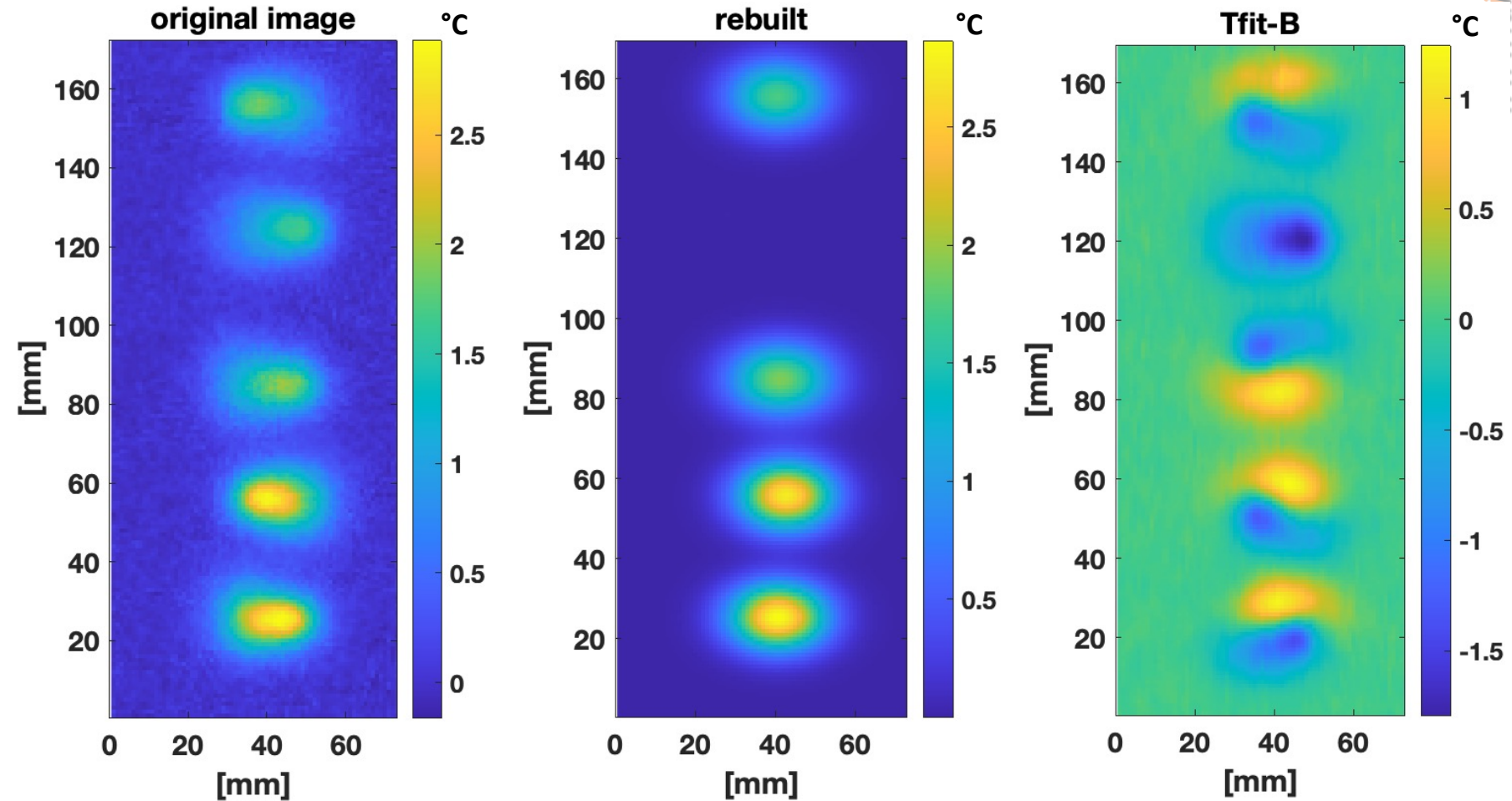
$$MSE = \frac{1}{N} \sum_N (RealImage - Smooth)^2$$

MAX Mean Squared Error between real image and smoothing: < 0.002%

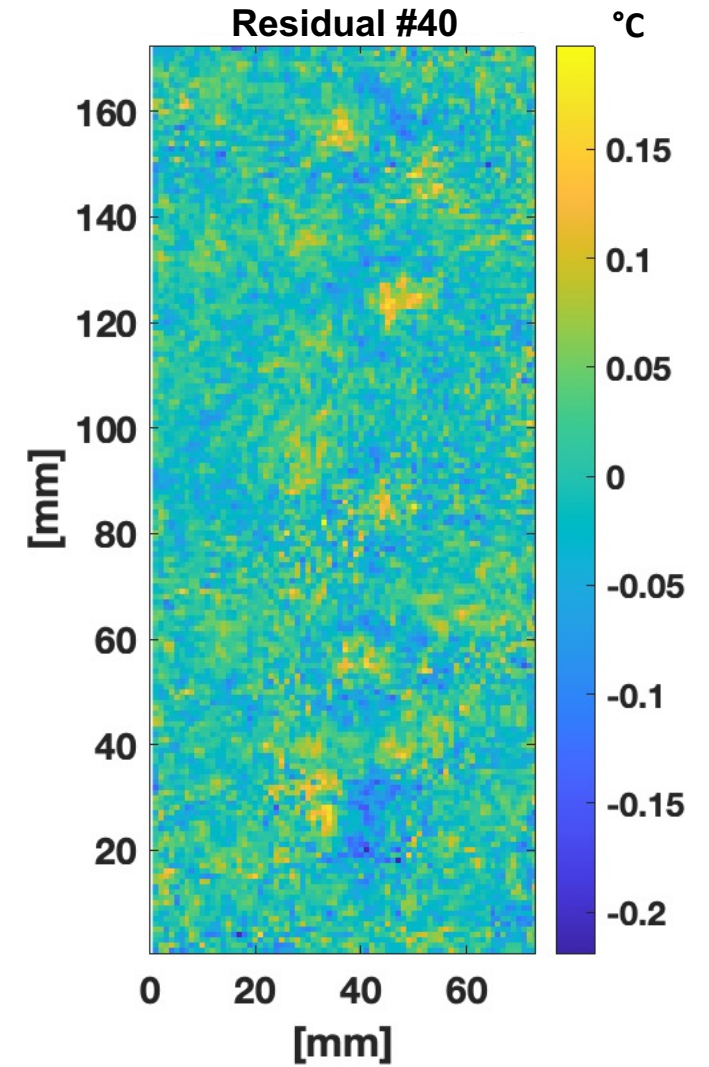
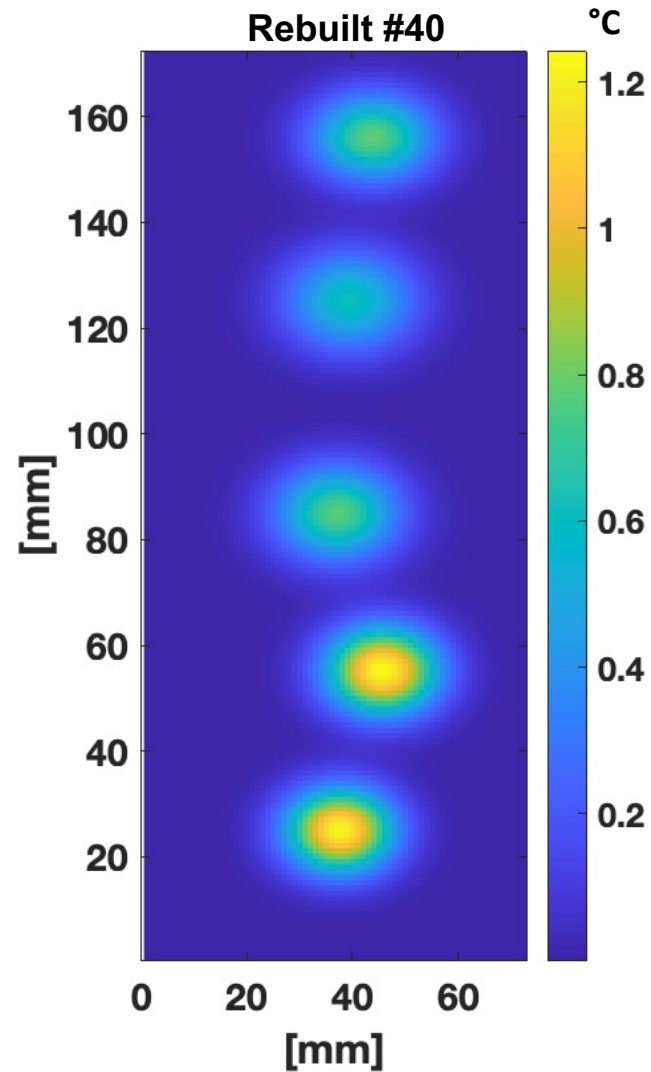
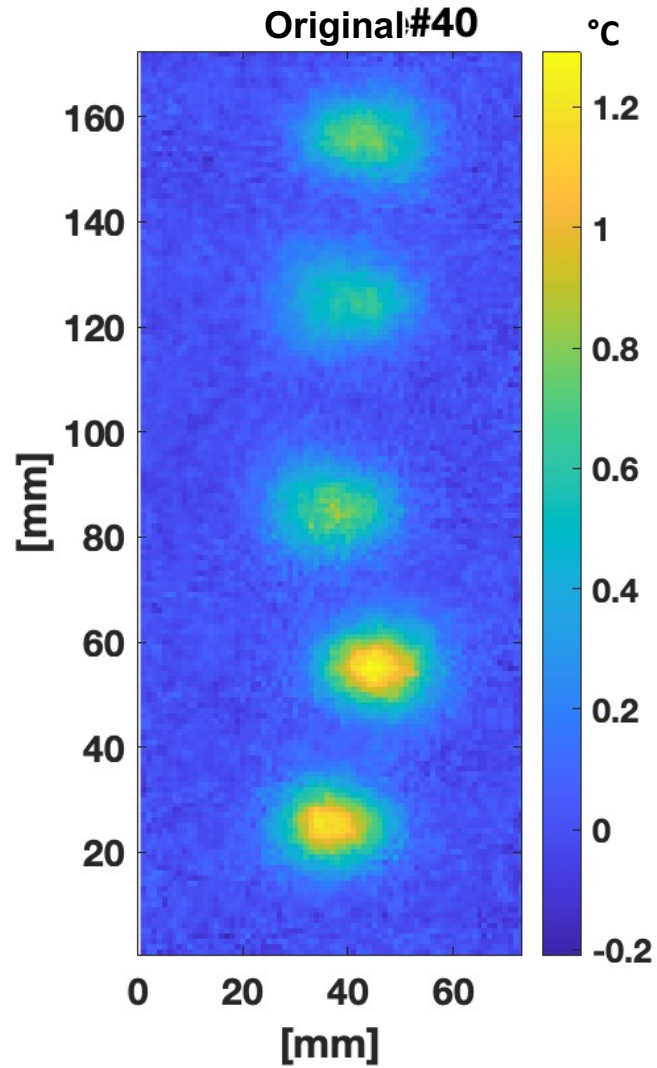


- Esc with  $\text{mse}(T, T^*) < 1e-3$ ;
- Found optimal  $\alpha = 1,5$  for the majority of experimental images;
- Solution didn't converge (NaN):  
 $\alpha = 0,01$ ;
- Negative Amplitude or sigmas:  
 $\alpha = 0,01$ ;
- for images n°107 and 293:  $\alpha = 1$ ;
- 3 single images:  $\alpha = 0,009$  for n°89 and 265;  $\alpha = 0,011$  for n°435;

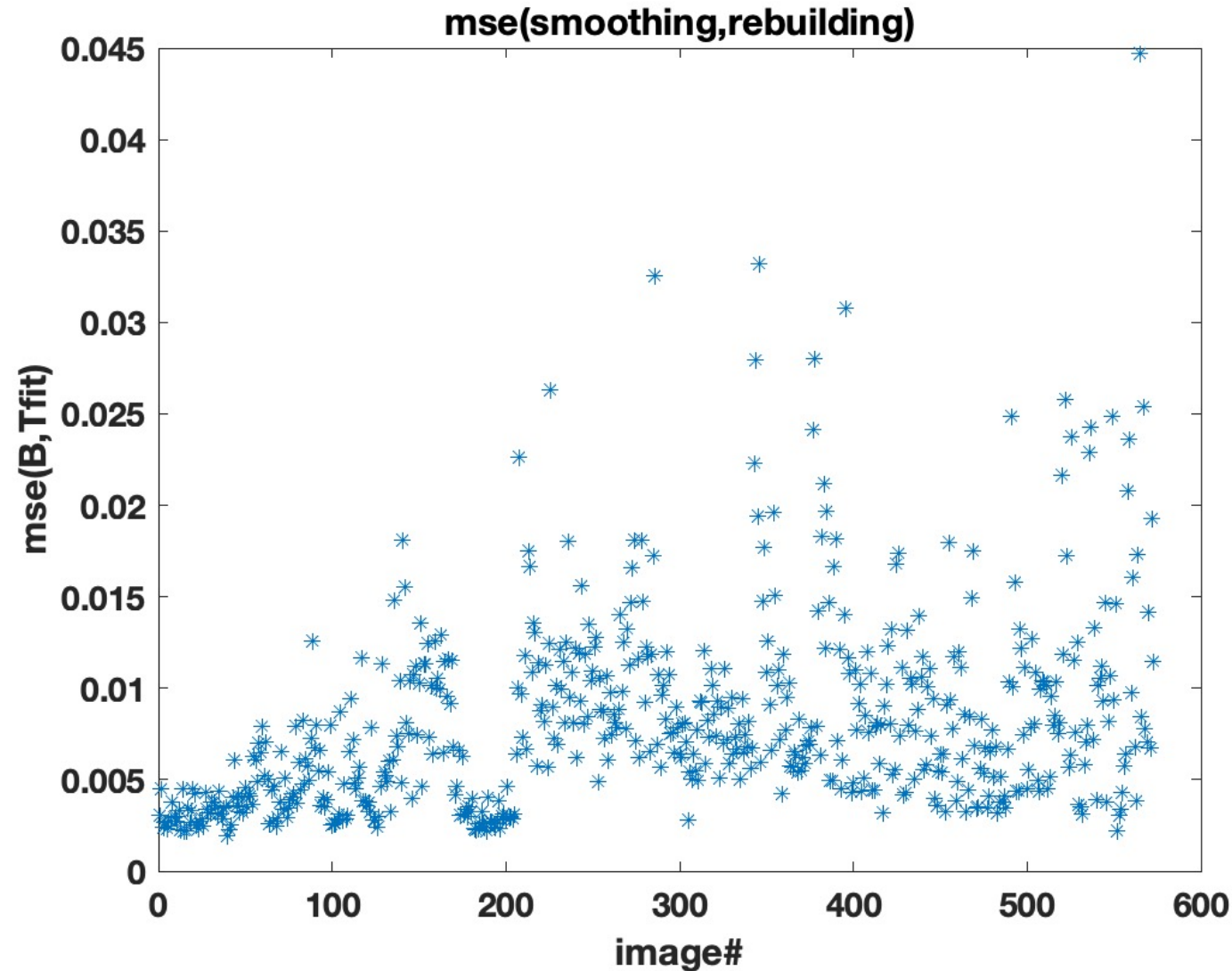
Worst Image: n°565



Best Image: n°40



Mean Squared Error between ReallImage\_smooth and RecImage



$$MSE = \frac{1}{N} \sum_N (RealImage' - Fit)^2$$

RealImage' = Smooth(Realimage)

## PRONS AND CONS OF NEWOTON'S METHOD:

- ✓ The regularization of the solution is more precise with this method
- The progress of the intermediate solution should be optimized depending on the context (depending on the type of image)
- It's probable that the advancement variable method is not the most suitable one that fits to our case
- x The convergence of the method is very sensitive to the goodness of the initial solution;

## FUTURE PERSPECTIVES:

- Tested an even more customizable method, such as the Machine Learning optimization method
- Development and testing of regularization methods of the solution
- Tile test with 80 beamlets (from 25 to 400 parameters)