

Università degli Studi di Padova – Dipartimento di Ingegneria Industriale

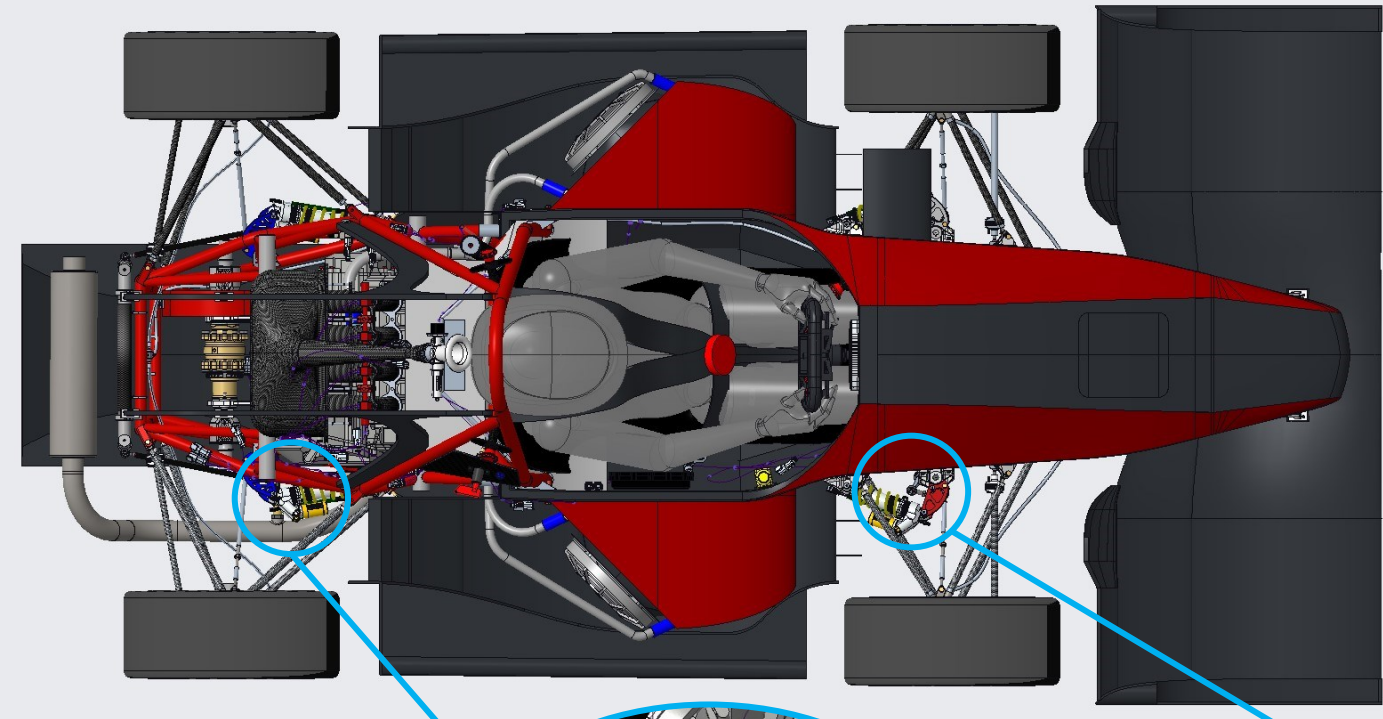
Corso di Laurea in Ingegneria Meccanica

***Relazione per la prova finale***  
***«Modellazione FEM e ottimizzazione topologica di un  
bilanciere per le sospensioni di una vettura da  
competizione»***

Tutor universitario: Prof. Gianluca Mazzucco

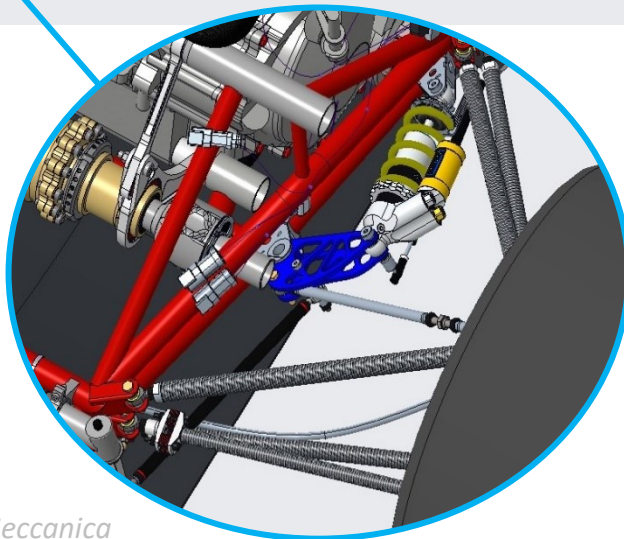
Laureando: *Zeno Pogacnik, 1190193*

Padova, 08/03/2023



## OBIETTIVI:

- Massimizzazione della **RIGIDEZZA**.
- Minimizzazione **MASSA**.
- Rispettare nuovi **INGOMBRI**.
- Geometria realizzabile per asportazione di truciolo.

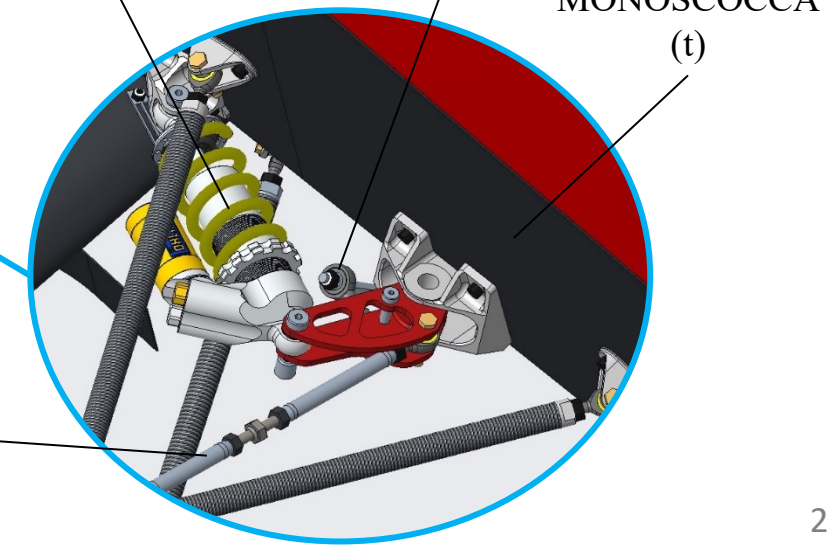


AMMORTIZZATORE  
(ammo)

ANTI-ROLL BAR  
(arb)

MONOSCOCCA  
(t)

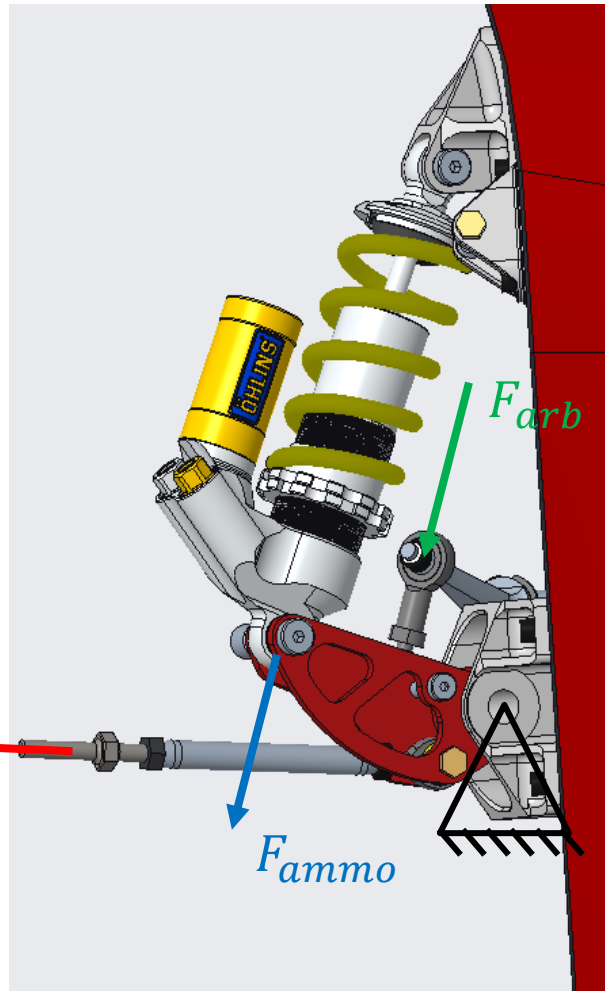
PULL-ROD  
(pull)





## ITER PROGETTUALE:

- Determinazione **FORZE** agenti e le loro componenti.
- Definizione **DESIGN SPACE**.
- Modellazione **MESH**.
- Impostazione delle **BC** per i vari **CASI STUDIO** e dei **PARAMETRI** di ottimizzazione.
- **SOVRAPPOSIZIONE** risultati al CAD e definizione nuova geometria.
- Ultima analisi **FEM** per valutare spostamenti e stato di tensione.



➤ Carichi con max latg= 2,4 g:

	$F_{amm}$ [N]	$F_{arb}$ [N]	$F_{pull}$ [N]
Anteriore	920	2200	9500
Posteriore	1350	2200	8500

➤ Componenti delle forze:

Anteriore			
	$F_{amm}$ [N]	$F_{arb}$ [N]	$F_{pull}$ [N]
$F_x$	0	-286.26	309.55
$F_y$	-913.42	-2114.98	-4063.80
$F_z$	-104.81	-533.79	8578.05

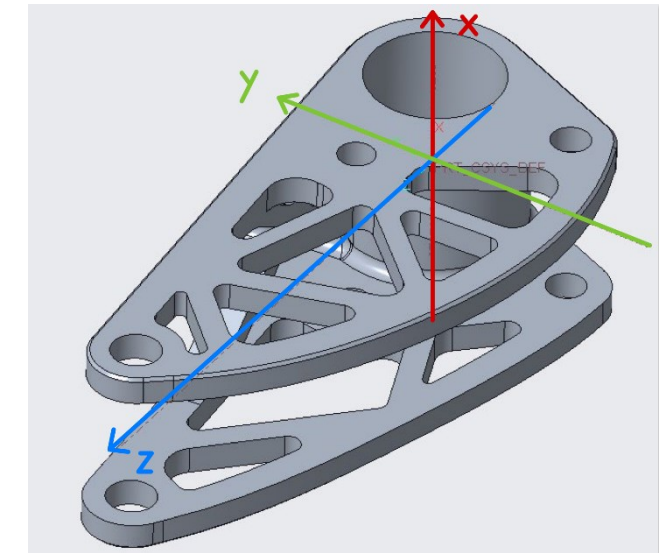
Posteriore			
	$F_{amm}$ [N]	$F_{arb}$ [N]	$F_{pull}$ [N]
$F_x$	0	-137.60	270.85
$F_y$	1315.96	-1841.87	4256.04
$F_z$	-301.68	1195.21	7352.72

➤ Casi studio:

	Vincoli	Sollecitazioni
$t_{amm}$	telaio; ammortizzatore	pull; arb
$t_{arb}$	telaio; arb	pull; ammortizzatore
$t_{pull}$	telaio; pull	arb; ammortizzatore

Tipologie vincoli considerati:

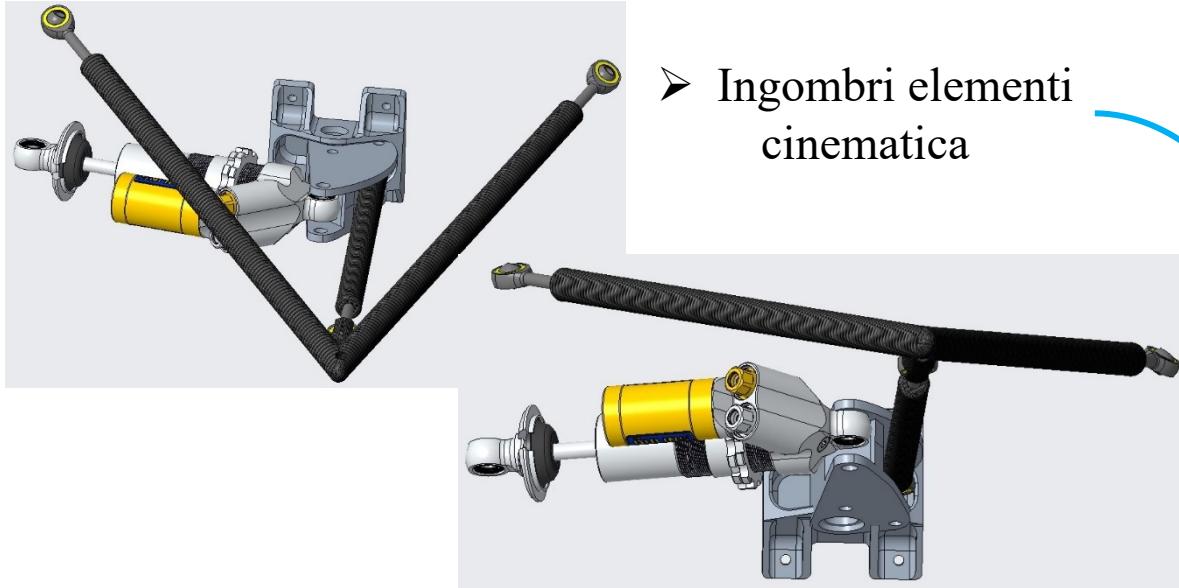
- Ammo e t: cilindrico
- Arb e Pull: sferico



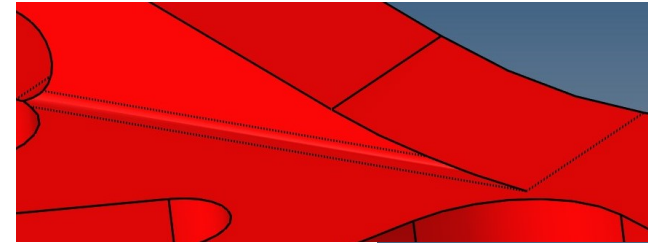
➤ Materiale:

	Ergal
Modulo elastico: (E) [MPa]	72000
Modulo di taglio: (G) [MPa]	27000
Coeff. di Poisson: ( $\nu$ ) [ ]	0.33
Densità: ( $\rho$ ) [ $ton/mm^3$ ]	$2.81 \times 10^{-9}$

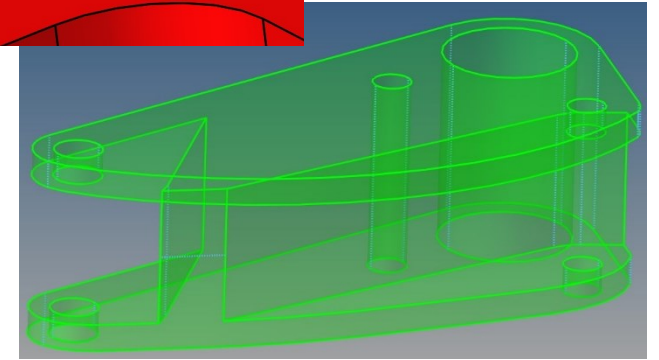




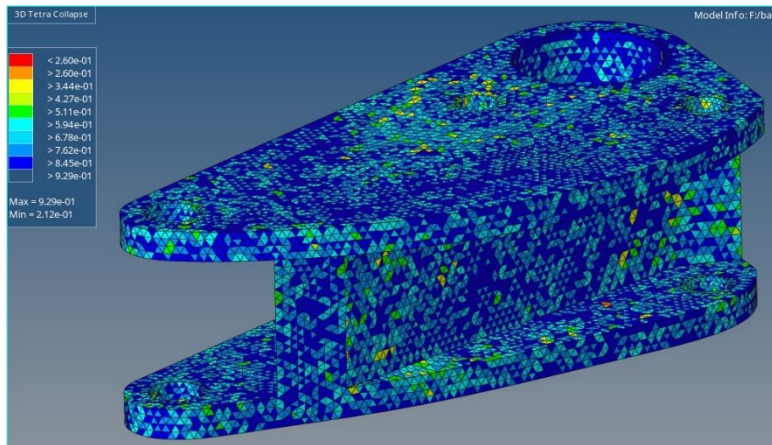
➤ Ingombri elementi cinematica



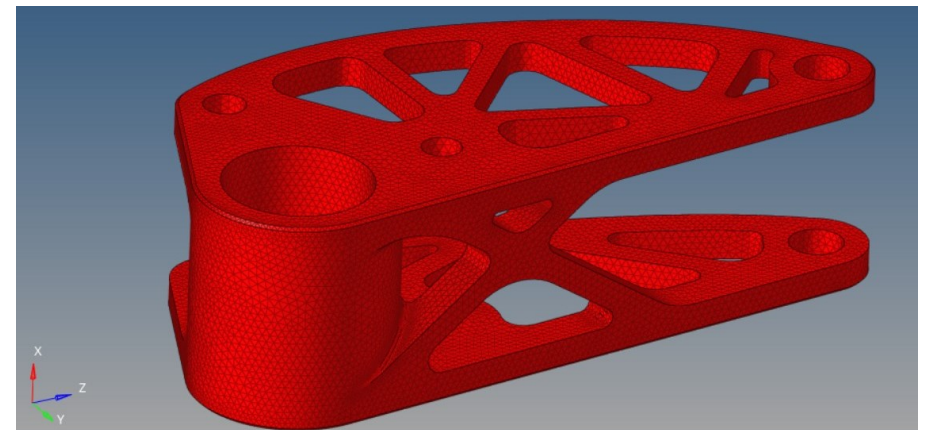
➤ Pulizia bordi superfici

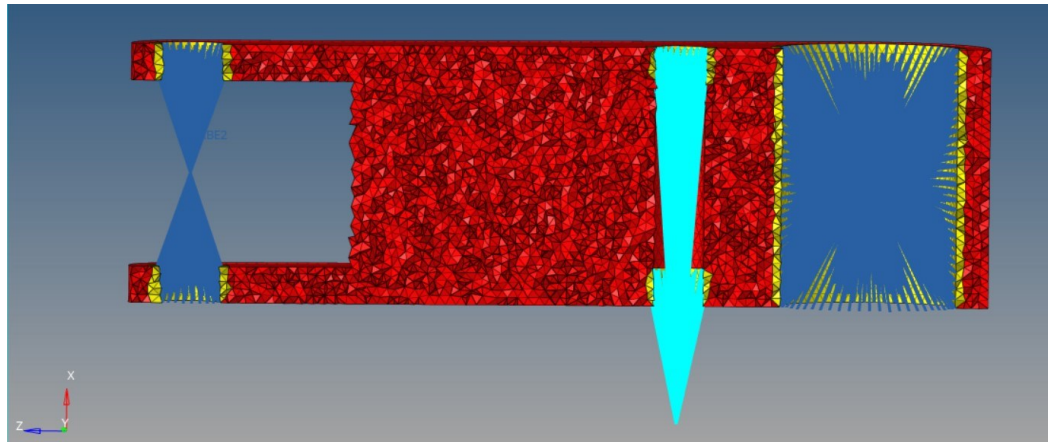


➤ Mesh tetraedrica

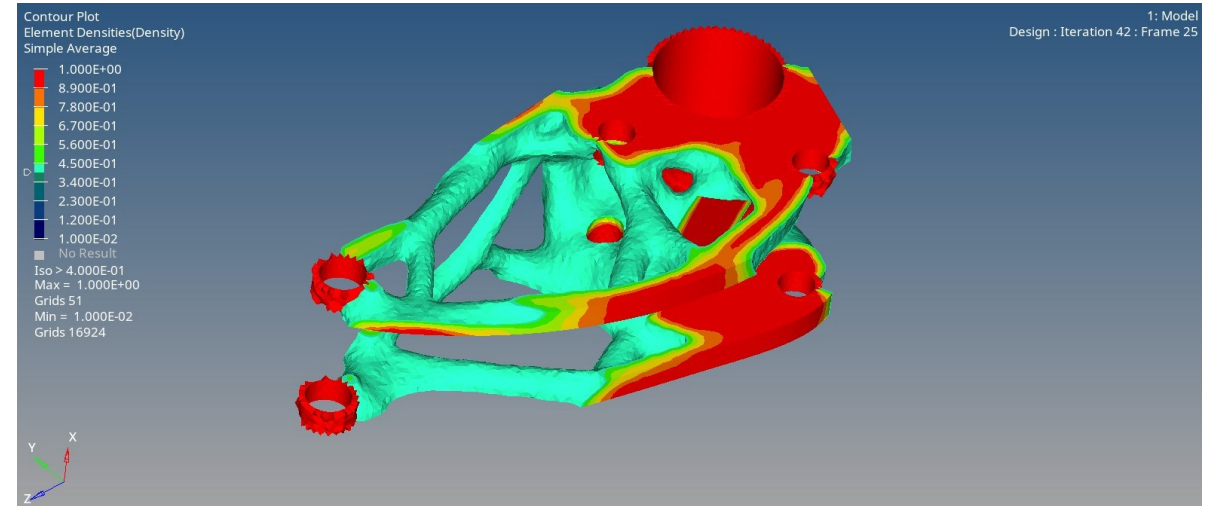


➤ Verifica della qualità degli elementi solidi

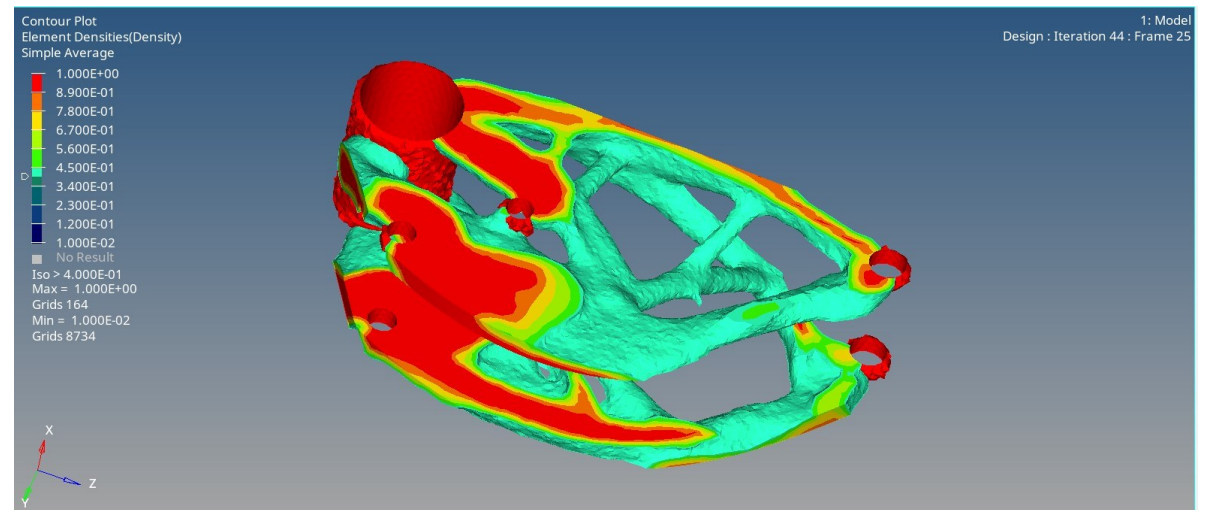




- DESVAR
  - MIN DIM
  - STRESS CONSTRAINT
  
- RESPONSES
  - VOLFRAC
  - STATIC DISPLACEMENT
  
- OBJECTIVE
  - min VOLFRAC
  
- DCONSTRAINTS
  - max STATIC DISPLACEMENT

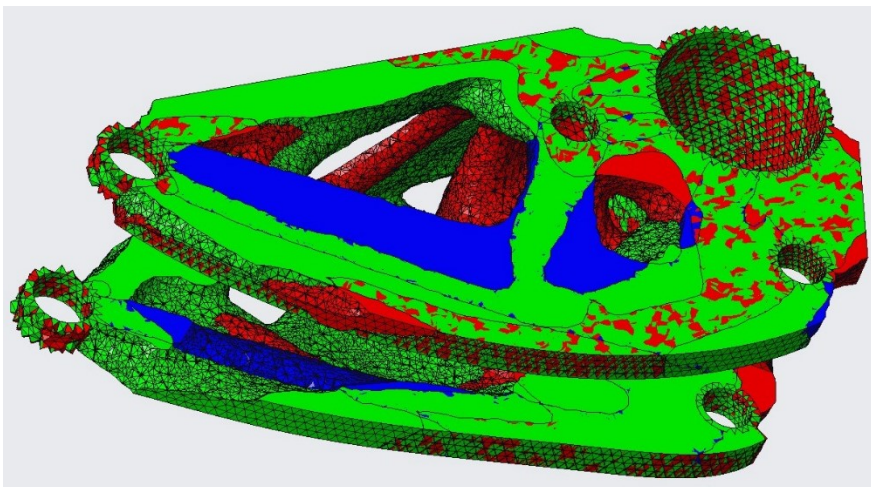


*Anteriore, caso  $t_{arb}$*

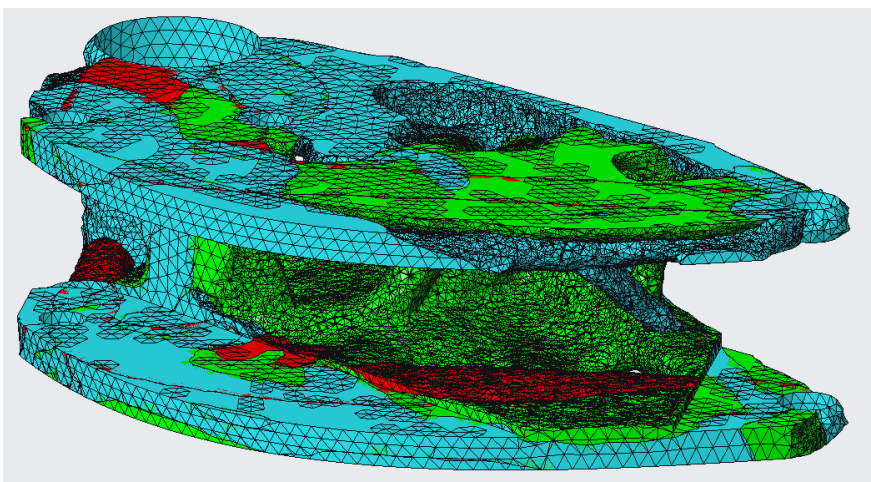


*Posteriore, caso  $t_{arb}$*

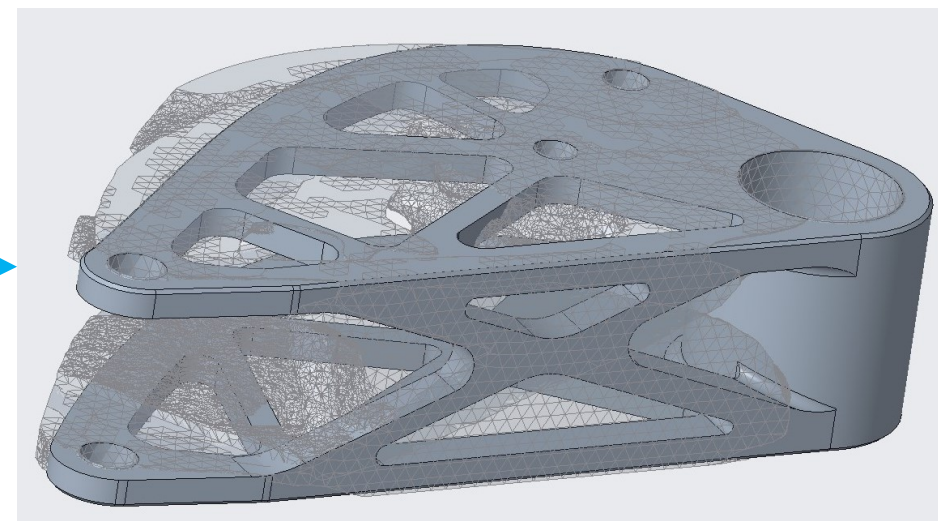
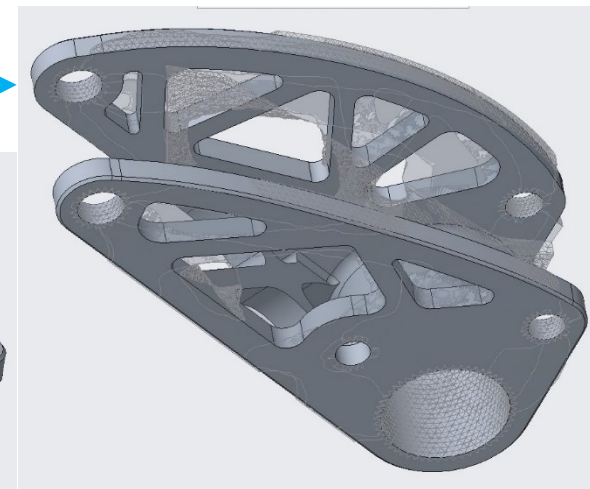
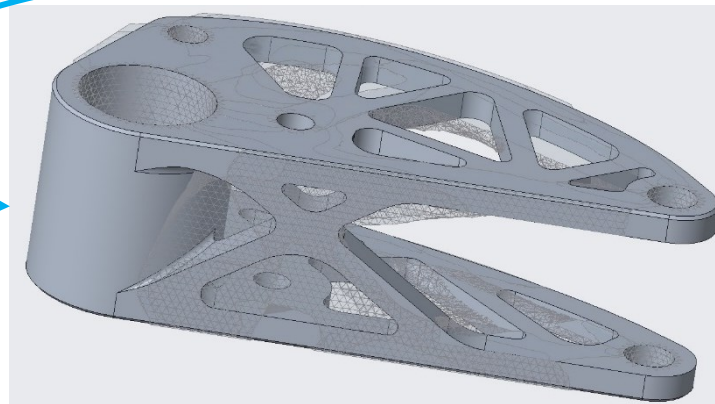




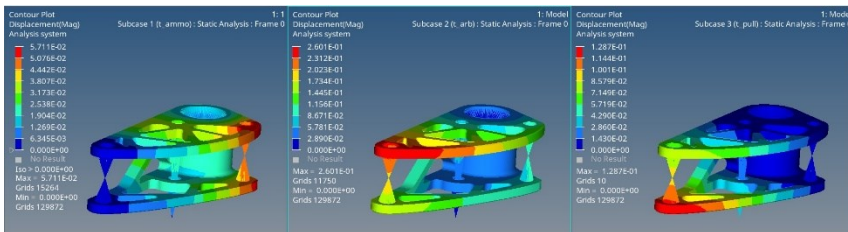
*Anteriore*



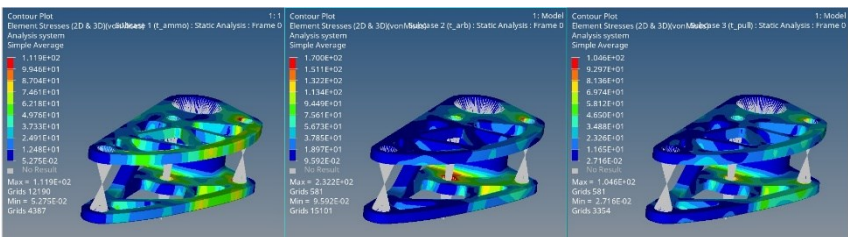
*Posteriore*



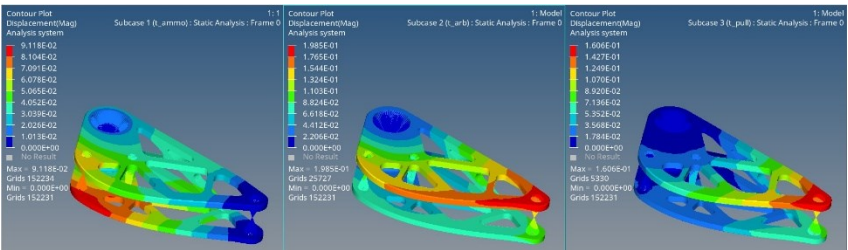




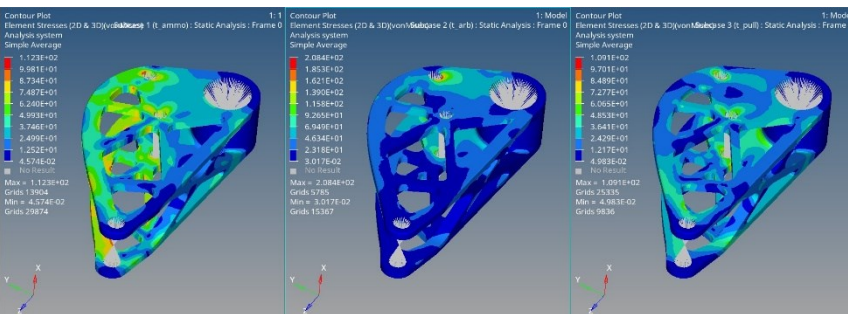
*Anteriore, spostamenti*



*Anteriore, tensioni Von Mises*



*Posteriore, spostamenti*



*Posteriore, tensioni Von Mises*

## ➤ COMPLIANCE

	ANTERIORE			POSTERIORE		
	Vecchia geometria	Nuova geometria	$\Delta C$ [%]	Vecchia geometria	Nuova geometria	$\Delta C$ [%]
$t_{amm}$	162.53 [Nmm]	178.45 [Nmm]	+8.92%	553.08 [Nmm]	341.21 [Nmm]	-38.31%
$t_{arb}$	241.41 [Nmm]	257.06 [Nmm]	+6.09%	248.88 [Nmm]	227.34 [Nmm]	-8.65%
$t_{pull}$	99.74 [Nmm]	81.80 [Nmm]	-21.94%	225.45 [Nmm]	126.34 [Nmm]	-43.96%

## ➤ STATIC DISPLACEMENT

	ANTERIORE			POSTERIORE		
	$t_{amm}$	$t_{arb}$	$t_{pull}$	$t_{amm}$	$t_{arb}$	$t_{pull}$
$\Delta s_{amm}$ [%]		-25.82%	-4.92%	+4.48%	-53.09%	
$\Delta s_{arb}$ [%]	-81.20%		-36.00%	-49.34%		-43.33%
$\Delta s_{pull}$ [%]	+42.28%	-17.44%		-27.49%	+18.09%	

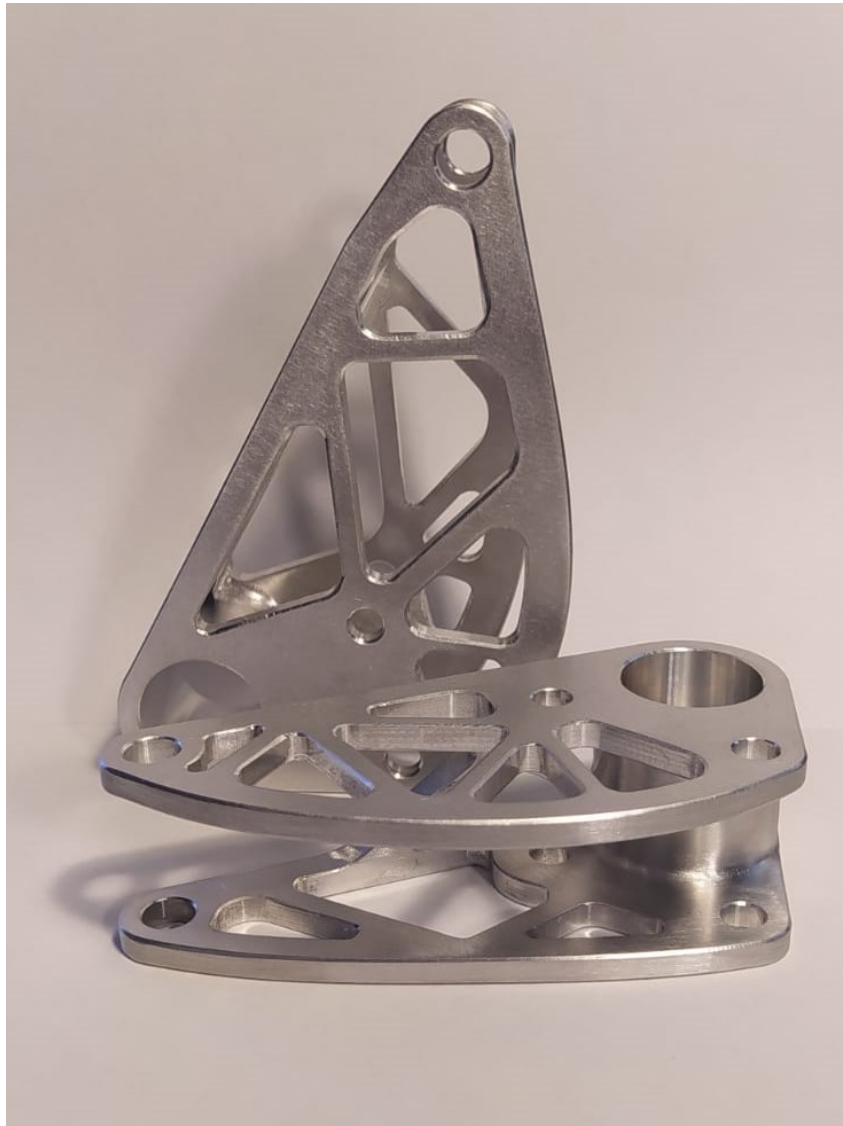
## ➤ COEFFICIENTI SICUREZZA CON CRITERIO VON MISES

	ANTERIORE				POSTERIORE			
	$\sigma_{vm}$ Vecchia geometria [MPa]	$\nu_S$	$\sigma_{vm}$ Nuova geometria [MPa]	$\nu_S$	$\sigma_{vm}$ Vecchia geometria [MPa]	$\nu_S$	$\sigma_{vm}$ Nuova geometria [MPa]	$\nu_S$
$t_{amm}$	149.1	3.42	111.9	4.56	221.2	2.31	112.3	4.54
$t_{arb}$	235.0	2.17	232.2	2.20	192.2	2.65	208.4	2.45
$t_{pull}$	146.7	3.48	104.6	4.89	171.2	2.98	109.1	4.67

## ➤ MASSA

	Vecchia geometria [g]	Nuova geometria [g]	$\Delta massa$ [%]
ANTERIORE	74.39	86.03	+15.66 %
POSTERIORE	88.06	102.6	+16.52 %





### OBIETTIVI FUTURI:

- Le  $F_{arb}$  e  $F_{pull}$  su piano (y, z) della squadretta.
- Additive manufacturing.